Electric Circuit Theory

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8.1 Introduction to the Natural Response of a Parallel *RLC* Circuit

First-Order Circuits (Chapter 7)

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- Circuits with a single storage element (a capacitor or an inductor).
- The differential equations describing them are first-order.



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Second-Order Circuits (Chapter 8)

- Circuits containing two storage elements
- > Their responses are described by differential equations that contain second derivatives.
- Typical examples of second-order circuits are RLC circuits.

A second-order circuit is characterized by a second-order differential equation. It consists of resistors and the equivalent of two energy storage elements.



> There are two basic types of RLC circuits: **parallel connected** and **series connected**.

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a Parallel *RLC* Circuit

Finding Initial Values

- > There are two key points to keep in mind in determining the initial conditions.
 - We must carefully handle the polarity of voltage $v_c(t)$ across the capacitor and the direction of the current $i_L(t)$ through the inductor.

Keep in mind that $v_c(t)$ and $i_L(t)$ are defined strictly according to the passive sign convention.

One should carefully observe how these are defined and apply them accordingly.

Keep in mind that the capacitor voltage is always continuous so that

 $v_c(0^+) = v_c(0^-)$

and the inductor current is always continuous so that

 $i_L(0^+) = i_L(0^-)$

where $t = 0^-$ denotes the time just before a switching event and $t = 0^+$ is the time just after the switching event, assuming that the switching event takes place at t = 0.

Thus, in finding initial conditions, we first focus on those variables that cannot change abruptly, capacitor voltage and inductor current.

8.1 Introduction to the Natural Response of a Parallel *RLC* Circuit

Obtaining of the Differential Equation for a Parallel RLC Circuit

- Parallel RLC circuits find many practical applications, notably in communications networks and filter designs.
- \succ Assume initial inductor current I_0 and initial capacitor voltage $V_0,$

$$i_L(0) = \frac{1}{L} \int_{-\infty}^0 v(t) dt = I_0$$

 $v_c(0) = V_o$

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Since the three elements are in parallel, they have the same voltage v across them. Applying KCL at the top node gives

$$i_{R} + i_{L} + i_{C} = 0$$

$$\frac{v}{R} + \frac{1}{L} \int_{-\infty}^{t} v(t)dt + C\frac{dv}{dt} = 0$$

$$\frac{v}{R} + \frac{1}{L} \int_{-\infty}^{0} v(t)dt + \frac{1}{L} \int_{0}^{t} v(t)dt + C\frac{dv}{dt} = 0$$
(8.1)

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Obtaining of the Differential Equation for a Parallel RLC Circuit

> Taking the derivative with respect to *t* results in

$$\frac{1}{R}\frac{dv}{dt} + \frac{v}{L} + C\frac{d^2v}{dt^2} = 0 \quad (8.2) \quad \longleftarrow \quad \frac{v}{R} + I_o + \frac{1}{L}\int_0^t v(t)dt + C\frac{dv}{dt} = 0 \quad (8.1)$$

> Dividing by C Arranging the derivatives in the descending order, we get

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0$$
 (8.3)

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> This is a second-order differential equation and is the reason for calling the RLC circuits in this chapter second-order circuits.

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Solution of the Differential Equation

Our experience in the preceding chapter on first-order circuits suggests that the solution is of exponential form. So we let

$$v(t) = Ae^{st} \tag{8.4}$$

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0$$
 (8.3)

where A and s are unknown constants.

Substituting Eq. (8.4) into Eq. (8.3) and carrying out the necessary differentiations, we obtain

$$As^{2}e^{st} + \frac{As}{RC}e^{st} + \frac{Ae^{st}}{LC} = 0$$

or
$$Ae^{st}\left(s^{2} + \frac{1}{RC}s + \frac{1}{LC}\right) = 0 \quad (8.5)$$

Since $e^{st} \neq 0$

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$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$
 (8.6)

We cannot A=0 as a general solution because the voltage is not zero for all time and Ae^{st} is the assumed solution we are trying to find.

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Solution of the Differential Equation

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$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$
 (8.6)

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0$$
 (8.3)

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- Eq.(8.6) is known as the characteristic equation of the differential Eq. (8.3), since the roots of the equation determine the mathematical character of v(t).
- > The two roots of Eq. (8.8) are

$$s_1 = -\frac{1}{2RC} + \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$
 (8.7)

$$s_2 = -\frac{1}{2RC} - \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$
 (8.8)

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Solution of the Differential Equation

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The two values of s in Eqs.(8.7) and (8.8) indicate that there are two possible solutions for i, each of which is of the form of the assumed solution in Eq. (8.4); that is,

$$v_{1} = A_{1}e^{s_{1}t} \qquad \qquad \frac{d^{2}v}{dt^{2}} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0 \quad (8.3)$$

$$v_{2} = A_{2}e^{s_{2}t}$$

- Since Eq. (8.3) is a linear equation, any linear combination of the two distinct solutions v₁ and v₂ is also a solution of Eq. (8.3).
- A complete or total solution of Eq. (8.3) would therefore require a linear combination of v₁ and v₂.
- > Thus, the **natural response** of the parallel RLC circuit is

 $v(t) = v_1 + v_2 = A_1 e^{s_1 t} + A_2 e^{s_2 t}$ (8.9)

where the constants A_1 and A_2 are determined from the initial values v(0) and dv(0)/dt .

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Solution of the Differential Equation

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> We can show that Eq.(8.9) also is a solution.

$$v(t) = A_{1}e^{s_{1}t} + A_{2}e^{s_{2}t} \quad (8.9)$$

$$\frac{dv}{dt} = A_{1}s_{1}e^{s_{1}t} + A_{2}s_{2}e^{s_{2}t} \qquad \frac{d^{2}v}{dt^{2}} = A_{1}s_{1}^{2}e^{s_{1}t} + A_{2}s_{2}^{2}e^{s_{2}t}$$

$$\frac{d^{2}v}{dt^{2}} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0 \quad (8.3)$$

$$A_{1}e^{s_{1}t}\left(s_{1}^{2} + \frac{1}{RC}s_{1} + \frac{1}{LC}\right) + A_{2}e^{s_{2}t}\left(s_{2}^{2} + \frac{1}{RC}s_{2} + \frac{1}{LC}\right) = 0 \quad (8.12)$$

• Each parenthetical term is zero because by definition s_1 and s_2 are roots of the characteristic equation.

$$s_{1}^{2} + \frac{1}{RC}s_{1} + \frac{1}{LC} = 0$$

$$s_{2}^{2} + \frac{1}{RC}s_{2} + \frac{1}{LC} = 0$$

$$s^{2} + \frac{1}{RC}s_{2} + \frac{1}{LC} = 0$$
(8.6)

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Chapter 8 Natural and Step Responses of *RLC* Circuits 8.1 Introduction to the Natural Response of a Parallel *RLC* Circuit

Definition of Frequency Terms

> We have shown that v_1 is a solution, v_2 is a solution, and v_1+v_2 is a solution. Therefore, the general solution of Eq.(8.3) has the form given in Eq.(8.13).

 $\nu(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$ (8.13), (8.9)

> The behavior of v(t) depends on the values of s_1 and s_2 .

$$s_1 = -\frac{1}{2RC} + \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}} = -\alpha + \sqrt{\alpha^2 - \omega_o^2}$$
 (8.14)

$$s_{2} = -\frac{1}{2RC} - \sqrt{\left(\frac{1}{2RC}\right)^{2} - \frac{1}{LC}} = -\alpha - \sqrt{\alpha^{2} - \omega_{o}^{2}}$$
(8.15)

$$\alpha = \frac{1}{2RC} \qquad (8.16) \qquad \qquad \omega_o = \frac{1}{\sqrt{LC}} \qquad (8.17)$$

Since the exponents s_1t and s_2t must be dimensionless, s_1 and s_2 must have the unit of "per second".

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Definition of Frequency Terms

- > Therefore, the units of α and ω_o must also be "per second" or s⁻¹. A unit of this type is called **frequency**.
- Let us define new terms:
 - Neper frequency (exponential damping coefficient)

 $\alpha = \frac{1}{2RC} \qquad (8.16)$

• Resonant frequency

$$\omega_o = \frac{1}{\sqrt{LC}} \qquad (8.17)$$

Complex frequency

$$S_1, S_2$$

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Types of Responses(solutions)

> From Eqs. (8.14),(8.15), we can infer that there are three types of solutions depending on the relative sizes of α and ω_o :

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$
 (8.14) $s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$ (8.15) $\alpha = \frac{1}{2RC}$ $\omega_0 = \frac{1}{\sqrt{LC}}$

• Overdamped response :

If $\alpha^2 > \omega_o^2$, both roots s₁ and s₂ are negative and real. $L > 4R^2C \rightarrow \alpha > \omega_o$

Critically damped response

If $\alpha^2 = \omega_o^2$, $s_1 = s_2 = -\alpha$ $L = 4R^2C \rightarrow \alpha = \omega_o$

Underdamped response

If $\alpha^2 < \omega_o^2$, both roots s₁ and s₂ are complex and, in addition, are conjugates of each other.

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_o^2} = -\alpha + \sqrt{-(\omega_o^2 - \alpha^2)} = -\alpha + j\omega_d$$

 $L < 4R^2C \rightarrow \alpha < \omega_o$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_o^2} = -\alpha - \sqrt{-(\omega_o^2 - \alpha^2)} = -\alpha - j\omega_d$$

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• What is the damping?

> Undamped System

The following physical systems are some examples of simple harmonic oscillator.





A release from rest at a position x_0 .

Chapter 8 Natural and Step Responses of RLC Circuits

8.2 The Forms of the Natural Response of a Parallel *RLC* Circuit

Electrical System

- The capacitor stores energy in its electric field E and the inductor stores energy in its magnetic field B (green).
- The charge flows back and forth between the plates of the capacitor, through the inductor.
- The energy oscillates back and forth between the capacitor and the inductor **until** (if not replenished from an external circuit) **internal resistance makes the oscillations die out**.

Energy oscillations in the LC Circuit and the mass-spring system



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Electrical System

- We now consider a RLC circuit which contains a resistor, an inductor and a capacitor.
- Unlike the LC circuit energy will be dissipated through the resistor.



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8.2 The Forms of the Natural Response of ______ a Parallel *RLC* Circuit

The Overdamped Voltage Response

> If $L > 4R^2C$, $\alpha > \omega_o$.

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The roots of the characteristic equation are negative real numbers.

$$s_{1} = -\alpha + \sqrt{\alpha^{2} - \omega_{o}^{2}}$$

$$\alpha = \frac{1}{2RC} \qquad \omega_{o} = \frac{1}{\sqrt{LC}}$$

$$s_{2} = -\alpha - \sqrt{\alpha^{2} - \omega_{o}^{2}}$$



The response is

 $v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \tag{8.18}$

The process for finding the overdamped response, v(t):

- (1) Find s_1 and s_2 , using the values of R, L, and C.
- (2) Find $v(0^+)$ and $dv(0^+)/dt$.
- (3) Find the values of A_1 and A_2 using $v(0^+)$ and $dv(0^+)/dt$.
- (4) Substitute the values for s_1 , s_2 , A_1 and A_2 into Eq.(8.18).

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a Parallel *RLC* Circuit

The Overdamped Voltage Response

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- The process for finding the overdamped response, v(t):
 - (2) Find $v(0^+)$ and $dv(0^+)/dt$.
 - Two initial conditions

 $v(0^+) = V_o$

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$$i_{C} = C \frac{dv}{dt} = -\frac{i_{L}(0^{+}) + i_{R}(0^{+})}{C}$$

$$= -\frac{I_{0}}{C} - \frac{V_{0}}{CR}$$

$$(8.21)$$

$$i_{C} + i_{L} + i_{R} = 0$$

$$i_{C} + i_{R} + i_{R} + i_{R} = 0$$

$$i_{C} + i_{R} + i_$$

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The Overdamped Voltage Response

The process for finding the overdamped response, v(t):

(3) Find the values of A_1 and A_2 using $v(0^+)$ and $dv(0^+)/dt$.

$$v(t) = A_{1}e^{s_{1}t} + A_{2}e^{s_{2}t}$$
(8.18)

$$v(0^{+}) = A_{1} + A_{2} = V_{0}$$
(8.23)

$$\frac{dv(t)}{dt} = s_{1}A_{1}e^{s_{1}t} + s_{2}A_{2}e^{s_{2}t}$$

$$\frac{dv(0^{+})}{dt} = s_{1}A_{1} + s_{2}A_{2}$$
(8.24)

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The Underdamped Voltage Response

For L < 4R²C, α < $ω_o$.

The roots of the characteristic equation are complex, and the response is underdamped.

$$s_{1} = -\alpha + \sqrt{\alpha^{2} - \omega_{o}^{2}} = -\alpha + \sqrt{-(\omega_{o}^{2} - \alpha^{2})} = -\alpha + j\sqrt{(\omega_{o}^{2} - \alpha^{2})} = -\alpha + j\omega_{d} \qquad (8.25)$$

$$s_{2} = -\alpha - \sqrt{\alpha^{2} - \omega_{o}^{2}} = -\alpha - j\omega_{d} \qquad (8.26)$$

$$\omega_{d} = \sqrt{\omega_{o}^{2} - \alpha^{2}} \qquad \alpha = \frac{1}{2RC} \qquad \omega_{o} = \frac{1}{\sqrt{LC}}$$

> The response is

 $v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$ (8.28)

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8.2 The Forms of the Natural Response of a Parallel *RLC* Circuit

The Underdamped Voltage Response

Finding The Underdamped Voltage Response

 $\nu(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$ (8.28)

The natural response is

$$v(t) = A_1 e^{-(\alpha - j\omega_d)t} + A_2 e^{-(\alpha + j\omega_d)t}$$

= $e^{-\alpha t} (A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t})$

$$\leftarrow v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$
$$s_1 = -\alpha + j\omega_d$$
$$s_1 = -\alpha - j\omega_d$$

Using Euler's identities,

$$e^{j\theta} = \cos\theta + j\sin\theta$$
 $e^{-j\theta} = \cos\theta - j\sin\theta$ (8.29)

We get

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$$v(t) = e^{-\alpha t} [A_1(\cos \omega_d t + j \sin \omega_d t) + A_2(\cos \omega_d t - j \sin \omega_d t)]$$
$$= e^{-\alpha t} [(A_1 + A_2) \cos \omega_d t + j(A_1 - A_2) \sin \omega_d t]$$

 $v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \quad (8.28)$

$$B_1 = A_1 + A_2$$
 $B_2 = j(A_1 - A_2)$



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The Underdamped Voltage Response

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 $\nu(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$ (8.28)

With the presence of sine and cosine functions, it is clear that the natural response for this case is exponentially damped and oscillatory in nature.

The response has a time constant of $1/\alpha$ and a period of $T = 2\pi/\omega_d$.

Figure depicts a typical underdamped response. [Figure assumes for each case that i(0) = 0].





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The Critically Damped Voltage Response

$$\succ$$
 If $L = 4R^2C$, $\alpha = \omega_o$.

The two roots of the characteristic equation are real and equal.

$$s_{1} = -\alpha + \sqrt{\alpha^{2} - \omega_{o}^{2}} = -\alpha$$

$$s_{1} = s_{2} = -\alpha = -\frac{1}{2RC} \quad (8.32)$$

$$\alpha = \frac{1}{2RC} \qquad \omega_{o} = \frac{1}{\sqrt{LC}}$$

> The response is

 $v(t) = (D_1 t + D_2)e^{-\alpha t}$ (8.34)

8.2 The Forms of the Natural Response of _____ a Parallel *RLC* Circuit

The Critically Damped Voltage Response

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Finding the natural response (Eq.8.34)

$$\frac{d^{2}v}{dt^{2}} + \frac{1}{RC}\frac{dv}{dt} + \frac{v}{LC} = 0 \qquad (1) \qquad (8.3)$$

$$\alpha = \omega_{0} = \frac{1}{2RC} = \frac{1}{\sqrt{LC}}$$

$$\frac{d^{2}v}{dt^{2}} + 2\alpha\frac{dv}{dt} + \alpha^{2}v = 0 \qquad (2)$$

$$\frac{d}{dt}\left(\frac{dv}{dt} + \alpha v\right) + \alpha\left(\frac{dv}{dt} + \alpha v\right) = 0 \qquad (3)$$
If we let
$$f = \frac{dv}{dt} + \alpha v \qquad (4)$$

$$F = A_{1}e^{-\alpha t} \qquad (6)$$
Eq.(4) then becomes
$$\frac{dv}{dt} + \alpha v = D_{1}e^{-\alpha t} \qquad (6)$$

(5)

then Eq.(3) becomes

$$\frac{df}{dt} + \alpha f = 0$$

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This can be written as

 $\frac{d(e^{\alpha t}v)}{d(e^{\alpha t}v)} = D_1$

dt

(8)

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(7)

8.2 The Forms of the Natural Response of a Parallel *RLC* Circuit

The Critically Damped Voltage Response

Finding the natural response (Eq.8.34)

$$\frac{d(e^{\alpha t}v)}{dt} = D_1$$

Integrating both sides yields

 $d(e^{\alpha t}v)=D_1dt$

$$e^{\alpha t} v = D_1 t + D_2 \tag{9}$$

or

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 $v(t) = (D_1 t + D_2)e^{-\alpha t}$ (8.34)

This is a typical critically damped response. The natural response of the critically damped circuit is a sum of two terms: a negative exponential and a negative exponential multiplied by a linear term.

(8)







Responses of Parallel RLC Circuit

Natural Response: Summary

- The circuit is being excited by the energy initially stored in the capacitor and inductor.
- The energy is represented by the initial capacitor voltage V_o and initial inductor current I_o .
- Thus, at t = 0,

$$v_C(0) = \frac{1}{C} \int_{-\infty}^{0} i(t) dt = V_0 \qquad i(0) = I_0$$

• Overdamped response: $\alpha^2 > \omega_o^2$ $L > 4R^2C$

Both roots s_1 and s_2 are negative and real.

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_o^2}$$
 $s_2 = -\alpha - \sqrt{\alpha^2 - \omega_o^2}$ $v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$

• Underdamped response: $\alpha^2 < \omega_o^2$ $L < 4R^2C$

The roots of the characteristic equation are complex.

 $s_1 = -\alpha + j\omega_d$ $s_2 = -\alpha - j\omega_d$

$$v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

• **Critically damped response:** $\alpha^2 = \omega_o^2$ $L = 4R^2C$ The two roots of the characteristic equation are real and equal.

 $s_1 = s_2 = -\alpha$

 $v(t) = (D_1 t + D_2)e^{-\alpha t}$



Responses of Parallel RLC Circuit

Step Response

• The step response is obtained by the sudden application of a dc source.



- We want to find i due to a sudden application of a dc current.
- To develop a general approach to finding the step response of a second order circuit, we focus on finding the current in the inductor branch, i_L .

This current does not approach zero as t increases.

$$i_L(\infty) = l$$

Step Response

• Applying KCL at the top node for t > 0,

 $i_L + i_R + i_C = I$

or

$$i_L + \frac{v}{R} + C \frac{dv}{dt} = I \tag{8.37}$$

• From the definition

$$v = L \frac{di_L}{dt}$$
(8.38)

 $\frac{dv}{dt} = L \frac{d^2 \iota_L}{dt^2}$ (8.39)

• Substituting Eqs.(8.38) and (8.39) into Eq.(8.37) gives

$$i_{L} + \frac{L}{R}\frac{di_{L}}{dt} + LC\frac{d^{2}i_{L}}{dt^{2}} = I$$
(8.40)
$$\frac{d^{2}i_{L}}{dt^{2}} + \frac{1}{RC}\frac{di_{L}}{dt} + \frac{i_{L}}{LC} = \frac{I}{LC}$$
(8.41)

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Step Response

$$\frac{d^2 i_L}{dt^2} + \frac{1}{RC} \frac{d i_L}{dt} + \frac{i_L}{LC} = \frac{I}{LC}$$
(8.41)

 The complete solution to Eq. (8.41) consists of the natural response *i_n* and the forced response *i_f*; that is,,

 $i_L(t) = i_n(t) + i_f(t)$

• The natural response is the same as what we had in Section 8.2.

 $\begin{aligned} v(t) &= A_1 e^{s_1 t} + A_2 e^{s_2 t} & i_n(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} \\ v(t) &= e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) & i_n(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \\ v(t) &= (D_1 t + D_2) e^{-\alpha t} & i_n(t) = (D_1 t + D_2) e^{-\alpha t} \end{aligned}$

The forced response is the steady state or final value of *i*.
 In the circuit in Fig.8.11, the final value of the current through the inductor is the same as the source current *I*. Thus,

 $i_f(t) = I$

Step Response

• The complete solutions:

 $i_L(t) = i_n(t) + i_f(t)$

Overdamped response

$$i_n(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$i_f(t) = I$$

$$i_L(t) = I + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$
(8.47)

Underdamped response

$$i_n(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

$$i_f(t) = I$$

$$i_L(t) = I + e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \quad (8.48)$$

Critically damped response

$$i_n(t) = (D_1 t + D_2)e^{-\alpha t}$$

$$i_f(t) = I$$

$$i_L(t) = I + (D_1 t + D_2)e^{-\alpha t}$$
(8.49)